High-Performance LiDAR Sensor for KINEMATIC Laser Scanning

very high measurement rate up to 1,000,000 meas./sec

- very high scan speed up to 250 scans / second
- 5 mm survey-grade accuracy
- field of view 360° for unrestricted data acquisition
- regular point pattern, perfectly parallel scan lines
- cutting edge RIEGL technology providing:
 - echo signal digitization
 - online waveform processing
 - multiple-time-around processing
- multiple target capability practically unlimited number of target echoes
- compact (227x180x125 mm), lightweight (3.5 kg), and rugged
- userfriendly mounting
- mechanical and electrical interface for IMU mounting
- electrical interfaces for GPS data string and sync pulse (1PPS)
- LAN-TCP/IP interface
- scan data storage on internal 240 GByte SSD memory

RIEGL's VUX-1HA High Accuracy kinematic LiDAR sensor is a very high speed, non-contact profile measuring system using a narrow laser beam and a fast line scanning mechanism, enabling full 360 degree beam deflection without any gaps.

High performance pulsed laser ranging, based on *RIEGL*'s well-proven echo signal digitization technology with subsequent online waveform processing results in superior measurement capabilities even under adverse athmospheric conditions and in excellent multiple target echo discrimination.

The *RIEGL* VUX-1HA is a compact and lightweight laser scanner, mountable in any orientation and even under limited space conditions on land based vehicles, tunnel measuring devices, watercraft, etc.

The instrument needs only one power supply and provides line scan data via the integrated LAN-TCP/IP interface. The binary data stream can easily be decoded by user-designed software making use of the available software library RiVLib.

Typical applications include

- Mobile Laser Mapping
- Tunnel Profile Measurement
- Railway Applications like Clearance Analysis, etc



visit our website www.riegl.com

Mobile Laser Scanning

Laser Product Classification

Class 1 Laser Product according to IEC60825-1:2007 The following clause applies for instruments delivered into the United States: Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007.



Range Measurement Performance

Measuring Principle

time of flight measurement, echo signal digitization, online waveform processing, multiple-time-around-capability

| Laser Pulse Repetition Rate PRR ¹⁾ | 300 kHz | 500 kHz | | | 100 full power | | |
|-------------------------------------------------------------------------------------------------------------|--------------------------------------------|----------------|----------------|---------------|----------------------|---------------|--|
| Max. Measuring Range ^{3) 4)} natural targets $\rho \ge 10$ % natural targets $\rho \ge 80$ % | 150 m 420 m | 120 m 330 m | 100 m 270 m | 50 m 135 m | 85 m 235 m | 40 m 120 m | |
| Max. Number of Targets per Pulse | practically unlimited (details on request) | | | | | | |

1) Rounded values

 I bounded values.
 I base power optimized (reduced) for measurements of short ranges with high pulse repetition rate.
 I base power optimized (reduced) for measurements of short ranges with high pulse repetition rate.
 I prical values for average conditions. Maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. In bright sunlight, the max. range is shorter than under overcast sky.
 In order to reduce MIA ambiguities in mobile mapping applications it is recommended to use measurement programs with reduced laser power for short range applications. and programs with reduced pulse repetition rate for long range applications.

| Minimum Range Accuracy ^{5) 7)} Precision ^{6) 7)} Laser Pulse Repetition Rate ^{1) 8)} Max. Effective Measurement Rate ¹⁾ Echo Signal Intensity Laser Wavelength Laser Beam Divergence Laser Beam Footprint (Gaussian Beam Definition) | 1.2 m 5 mm 3 mm up to 1000 kHz up to 1 000 000 meas./sec. (@ 1000 kHz PRR & 360° FOV) for each echo signal, high-resolution 16 bit intensity information is provided near infrared 0.5 mrad ⁹ 4.5 mm @ exit, 5 mm @ 5 m, 6.6 mm @ 10 m, 13 mm @ 25 m, 25 mm @ 50 m, 50 mm @ 100 m |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Accuracy is the degree of conformity of a measured quantity to its actual (true) value. Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result. | One sigma @ 30 m range under <i>RIEGL</i> test conditions. User selectable. Measured at the 1/e² points. 0.50 mrad corresponds to an increase of 50 mm of beam diameter per 100 m distance. |
| Scanner Performance Scanning Mechanism Field of View (selectable) Scan Speed (selectable) Angular Step Width Δ ϑ (selectable) between consecutive laser shots Angle Measurement Resolution Internal Sync Timer | rotating mirror 360° "full circle" 10 - 250 revolutions per second, equivalent to 10 - 250 scans/sec $0.0036^\circ \le \Delta \ \vartheta \le 0.3^\circ$ 0.001° for real-time synchronized time stamping of scan data |

LAN 10/100/1000 Mbit/sec

LAN 10/100/1000 Mbit/sec or USB 2.0

for real-time synchronized time stamping of scan data scanner rotation synchronization

Scan Sync (optional) Data Interfaces

Configuration Scan Data Output **GNSS** Interface

Internal Memory **External** Camera External GNSS Antenna

General Technical Data

Power Supply Input Voltage / Consumption¹⁰⁾ Main Dimensions ¹⁰⁾ VUX-1HA without / with Cooling Fan Device Weight 10) VUX-1HA without / with Cooling Fan Device Humidity Protection Class Temperature Range 11)

10) without external IMU/GNSS, cooling fan device not in operation
 11) The instrument requires air convection with a minimum flow rate of 5 m/s for continuous operation at +15 °C and above. If the ne-cessary flow rate cannot be provided by the moving platform, the cooling fan device (included in the scope of delivery) has to be used.

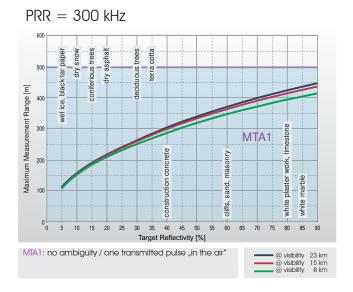
TTL input for 1PPS synchronization pulse 240 ĠByte SSD TTL input/output SMA connector 11 - 32 V DC / typ. 65 W

Serial RS232 interface for data string with GNSS-time information,

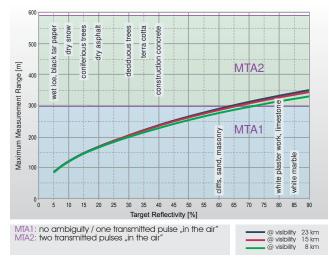
227 x 180 x 125 mm / 227 x 209 x 129 mm

approx. 3.5 kg / approx. 3.75 kg max. 80 % non condensing @ 31°C IP64, dust and splash-proof 0°C up to +40°C (operation) / -20°C up to +50°C (storage)

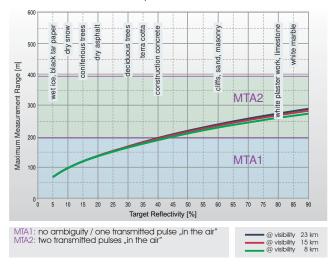
Maximum Measurement Range RIEGL VUX®-1HA

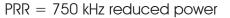


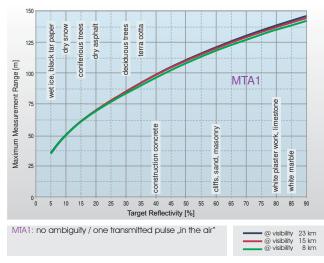
PRR = 500 kHz



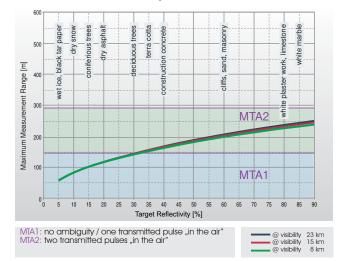
PRR = 750 kHz full power



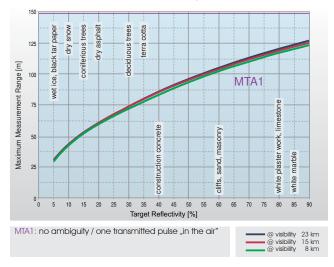




PRR = 1000 kHz full power







RIEGL VUX®-1HA Additional Equipment and Integration



Cooling Fan Device



RIEGL VUX-1HA with Protective Cap



RIEGL VUX-1HA with external IMU-Sensor (RIEGL VUX-SYS)

Additional Equipment for RIEGL VUX-1HA

Cooling Fan Device

Lightweight structure with two axial fans providing forced air convection for applications where sufficient natural air flow cannot be guaranteed. Power supply is provided via a connector on the rear side of the *RIEGL* VUX-1HA. The cooling fan device can be mounted either on the top side or on the bottom side of the *RIEGL* VUX-1HA and is included in the scanner's scope of delivery.

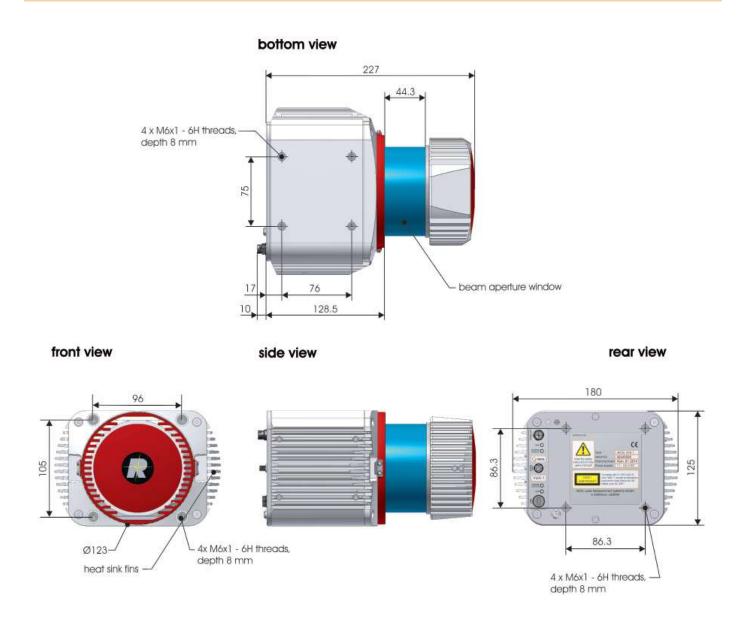
The cooling fan device is to be mounted whenever the environmental conditions/temperatures require (see "temperature range" on page 2 of this datasheet).

Protective Cap

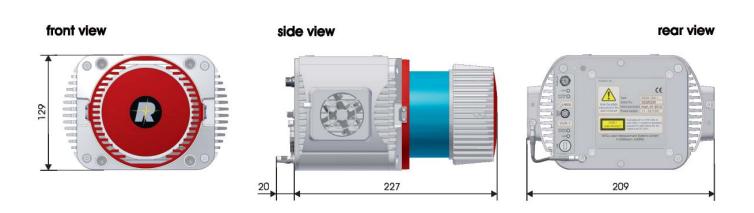
To shield the glass tube of the *RIEGL* VUX-1HA from mechanical damage and soiling, a protective cap is provided to cover the upper part of the instrument during transport and storage.

Options for RIEGL VUX-1HA Integration

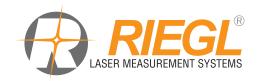
RIEGL is developing user-friendly, application- and installation-specific solutions for integration of the VUX-1HA LiDAR sensor into whatsoever type of moving platform.



Dimensional Drawings RIEGL VUX®-1HA with Cooling Fan Device



all dimensions in mm



RIEGL Laser Measurement Systems GmbH Riedenburgstraße 48 3580 Horn, Austria Phone: +43 2982 4211 | Fax: +43 2982 4210 office@riegl.co.at www.riegl.com

RIEGL USA Inc. Orlando, Florida | info@rieglusa.com | www.rieglusa.com **RIEGL Japan Ltd.** Tokyo, Japan | info@riegl-japan.co.jp | www.riegl-japan.co.jp RIEGL China Ltd. Beijing, China | info@riegl.cn | www.riegl.cn WWW.riegl.com



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Data Sheet, RIEGL VUX-1HA, 2016-09-16